# Transaction Costs, Communication and Spatial Coordination in Payment for Ecosystem Services Schemes\*

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## Abstract

Landowner participation and spatial coordination of land use decisions are key components for enhancing the effective delivery of ecosystem services from private land. However, inducing landowner participation in Payment for Ecosystem Services schemes for coordinating land management choices is challenging from a policy design perspective owing to transaction costs associated with participation. This paper employs a laboratory experiment to investigate the impact of such costs on participation and land use in the context of an Agglomeration Bonus (AB) scheme. The AB creates a coordination game with multiple Nash equilibria relating to alternative spatially-coordinated land use patterns. The experiment varies transaction costs between two levels (high and low), which affects the risks and payoffs of coordinating on the different equilibria. Additionally, the possibility of communication is implemented between neighboring landowners arranged on a local network to facilitate spatial coordination. Results indicate a significant difference in participation under high and low transaction costs, with a lower uptake when transaction costs are high. This effect is, however, impacted by transaction costs faced in the past. Communication improves AB performance with the effect being greater for participants facing high transaction costs.

Keywords: Agglomeration Bonus, Content Analysis, Coordination Games, Lab Experiments, Local Networks

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#### 1. Introduction

Payment for Ecosystem Services (PES) schemes offer landowners financial incentives for actions designed to increase the supply of ecosystem services from privately owned land (Hanley et al., 2012; Hanley and White, 2014). In many instances, spatial coordination is a desirable feature of such schemes, enabling the delivery of greater ecosystem service benefits compared to a situation where the uptake of contracts is spatially uncoordinated. Examples include greater biodiversity conservation benefits on farmland (Merckx et al., 2009; Dallimer et al., 2010; Wätzold et al., 2010), successful species reintroduction programmes and meta-population management on private land where habitat corridors permit wildlife movements, or where certain minimum sized contiguous habitat is needed (Williams et al., 2005; Önal and Briers, 2006), enhanced water quality improvements (Lane et al., 2004, 2006), and native vegetation restoration (Windle et al., 2009).

Since participation in PES schemes is voluntary, economists have looked for means of incentivising spatial coordination. One such a mechanism is the Agglomeration Bonus (AB), originally developed by Parkhurst et al. (2002) and Parkhurst and Shogren (2007). The AB is a mechanism landowners two-part payment where receive compensation for participating/enrolling, plus a bonus if neighboring landowners participate and select the same land use activity. In this format, the AB resembles a coordination game with multiple Nash equilibria pertaining to different land use choices. The Nash equilibria can be Pareto ranked by their payoffs. Laboratory experiments have indicated that such a payment structure can produce a range of desired spatial patterns of enrolled land parcels (Parkhurst and Shogren 2007; Warziniack et al., 2007). However, Banerjee et al. (2012, 2014) found that spatial coordination is challenging, and the AB can often fail to produce the desired spatial patterns owing to coordination failure.

Additionally, participation in any PES scheme is associated with landowner transaction costs (Shortle et al. 1998; Kampas and White, 2004). Examples of such costs include landowners' travel time to meetings with government officials, the time and cognitive effort of determining the relative payoffs of signing or not signing a contract, and the costs of engaging farm advisors, to name a few. Transaction costs have been shown to reduce participation in PES schemes (Falconer and Saunders, 2002; McCann et al., 2005; Mettepenningen et al., 2009). The AB, with its more complex design, is likely to create additional transaction costs such as those associated with negotiating with neighbors. It seems likely then that the success of the AB will be influenced by the size of transaction costs relative to the payoffs of enrolling. Yet, there has been no analysis to date on the effects of variations in transactions costs on the performance of the AB. The recent paper by Fooks et al. (2016) is perhaps closest to our study where the transaction costs are implicitly captured by a fixed submission fee. However, they study a conservation auction and not a subsidy scheme like we do.

Our paper poses two main research questions. First, what is the degree of participation and spatial coordination realized in AB schemes under different levels of transaction costs? Second, to what extent can communication between neighboring landowners improve AB performance by mitigating the negative effect of transaction costs? We answer these questions using a laboratory experiment. Lab experiments are useful to this study because they bypass the fact that it is not practical, and often even impossible, to exogenously manipulate the size of transaction costs for PES schemes participation in the field; and because only a few PES schemes in practice today include payments for spatial coordination (Kuhfuss et al., 2015).

Our experiment comprises groups of subjects who decide whether to participate in an AB scheme after paying a fixed fee – the transaction cost of participation. The transaction cost treatment is manipulated in a within-subject format. Since we are interested in strategic interactions and spatial coordination, we use a circular local network. On this type of network every individual is connected to two neighbors (to their left and to their right) directly and indirectly to the others (Jackson, 2010). While serving as a representative framework, this network structure allows us to contribute to the experimental literature on equilibrium selection and individual behavior in network coordination games (Berninghaus et al., 2002; Cassar, 2007). The network is also useful in implementing our between-subject communication treatment in a format representative of social interactions in agricultural communities where communication is expected to be more frequent between geographical neighbors than with everyone within a community.

Our results indicate that participation is significantly higher when transactions costs are low than when they are high. Moreover, in the event that individuals incur the transaction costs and participate, we observe higher rates of spatial coordination. The role of communication is not straightforward. Messaging unambiguously improves performance relative to no-communication situations when transaction costs are high. However, its efficacy in low transaction cost regimes depends upon whether subjects faced high costs previously and had previous experience with participating in the AB scheme.

# 2. The Strategic Environment

There are i = 1, ..., N landowners who face two simultaneous decision opportunities related to the AB scheme. The first decision entails whether or not to participate in the AB

scheme. If a landowner decides to participate, he or she can use his or her land for two different types of conservation land uses,  $\sigma_i = X, Y$ , which produce different levels and types of ecosystem services benefits. We assume that the ecosystem service benefits delivered from coordination of land use type X have greater agglomeration characteristics than for type Y, and the regulator sets the AB payments to reflect this ranking. Let  $\sigma_i = NP$  denote non-participation for landowner i whereby land is devoted to profit-based conventional agriculture, so that only agricultural returns are received. I

The AB scheme consists of two payoff components. The base component is a participation subsidy,  $s(\sigma_i)$ , intended to compensate for any opportunity cost of conservation relative to profit-maximising agricultural land use. Landowner i receives an additional bonus,  $b(\sigma_i)$ , if a neighboring landowner implements the same conservation land use practice as landowner i. Thus, the total bonus received is proportional to the number of neighboring landowners choosing the same land use strategy, denoted by  $n_{i\sigma}$ . We assume that the environmental agency provides AB payments for adoption of pro-conservation land use of one type only i.e. landowners cannot choose  $both\ X$  and Y. We make this assumption because (i) PES schemes typically involve a menu of land use practices from which landowners usually can select a few suitable ones, and (ii) paying some landowners for undertaking all listed actions may exhaust the limited PES budget (Cooper et al., 2009; Armsworth et al., 2012), creating high

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<sup>&</sup>lt;sup>1</sup> Traditional agricultural land use practices (denoted by *NP*) can also deliver ecosystem services such as reduction in soil erosion and biodiversity benefits by providing nesting and foraging habitats. These benefits are, however, not additional as they are associated with business-as-usual land use practices. Since one of the criteria for receiving ecosystem services payments is additionality (Wunder, 2007; Engel et al., 2008), such benefits should not be rewarded by the conservation agency. We therefore do not consider them in our model.

participation clusters in some areas at the expense of low participation rates elsewhere.<sup>2</sup> Let  $r(\sigma_i)$  denote the agricultural revenue under land use  $\sigma_i = X, Y, NP$ .

If a landowner i chooses to participate in the scheme he or she incurs transaction costs,  $T_i$ . We assume that all landowners have identical transaction costs, i.e.,  $T_i = T$ , either High or Low depending on the treatment. In practice, these transaction costs will vary substantially across landowners and across land use strategies. However, by sacrificing some realism (the presence of which would probably not cause large behavioral differences) we gain tractability that allows us to identify causal treatment effects. The payoff,  $u_i(\sigma_i)$ , of landowner i under the AB scheme reads as follows:

$$u_i(\sigma_i) = \begin{cases} r(\sigma_i) + s(\sigma_i) + n_{i\sigma}b(\sigma_i) - T & if \ \sigma_i = X,Y \\ r(\sigma_i) & if \ \sigma_i = NP \end{cases}$$
(1)

In Eq. (1) the number of neighbors and hence the bonus payments is contingent on the specific landscape structure. Following Banerjee et al. (2012, 2014), in this study we impose a simple circular network structure to represent neighborhood interactions. On this circular local network  $n_{i\sigma}$  can either take the value 0, 1 or 2. By using a circular network each individual faces the same level of strategic uncertainty, since all have the same number of neighbors. In contrast, in networks such as a two-dimensional lattice grid or a straight-line, where neighbourhood structure is asymmetric, individuals could respond to the transaction cost variation and information available through communication differently, potentially confounding our results. The payoff function specification in Eq. (1) makes the AB mechanism a coordination game with Nash Equilibria pertaining to situations where individuals and their neighbors choose the same

<sup>&</sup>lt;sup>2</sup> Such localized clustering may be interpreted as geographical targeting of conservation funds which can be politically contentious to the extent that the U.S. Congress has prohibited such targeting (Shortle et al., 2012).

strategy. This coordination game is similar to critical mass coordination games where the payoff from choosing an action is positive only if a specific number of players also choose that action (Devetag, 2003).

The AB coordination game has a Pareto efficient and multiple risk dominant Nash equilibria (Harsanyi and Selten 1988; Parkhurst et al., 2002). Strategy *X* corresponds to the Pareto efficient strategy as it generates the highest payoffs (because it has the greatest environmental benefits and hence highest agglomeration bonus). Strategy *Y* on the other hand constitutes a situation of coordination failure explained by the presence of strategic uncertainty within the game environment. That is, it might be less risky for a subject not to choose the efficient strategy and choose the land use practice that corresponds to a lower payoff *loss* in the event that one or more of the neighbors chooses not to coordinate on the efficient outcome. Strategy *NP* is also an equilibrium strategy but does not involve participating in the game.

Appendix B.I contains all parameters that have been used to construct the Payoff Tables 1a and 1b for the High (T = 40) and Low (T = 15) transaction cost treatments, respectively. We chose these values with attention to specific details of the strategic environment. Under the high-cost condition, the game features two Nash equilibria:  $\sigma_i = X$  ( $\forall i$ ) and the outside option  $\sigma_i = NP$  ( $\forall i$ ). Choosing land use practice Y is not a Nash equilibrium because it is strictly dominated by NP. Therefore, if a subject chooses to pay the fee and participate in the scheme, he or she would be likely to choose X over Y. This is an interesting setting because the presence of the fee reduces strategic uncertainty and the coordination problem in the event of participation. The forward induction principle that involves making an inference about the future play in a subgame based on information about play leading up to the subgame (Van Huyck et al., 1993; Cooper et al., 1994; Cachon and Camerer, 1996; Plott and Williamson, 2000) can then guide behavior

towards making the efficient X choice. In contrast, for the low transaction cost setting, selection of Y by a landowner and both direct neighbors leads to a payoff which is not strictly dominated by the reservation payoff, yielding a third Nash equilibrium  $\sigma_i = Y(\forall i)$ . The forward induction selection principle is not applicable in this setting.

Further, for the high transaction cost setting, T is greater than the participation payment for strategy X only. We chose this format because if the transaction cost is less than the participation components for both X and Y, participation is trivially incentivized even in the presence of the transaction cost and in the absence of the bonus. This is not an interesting case. The high-cost T value is not set to be greater than the participation payments for both strategies as well because this feature would further reduce landowner appeal to participate in the AB scheme. Under the low-cost condition, the transaction cost value is less than the participation component for both X and Y to generate a situation where participation is individually rational. We did not set T to be greater than both the participation components for reasons similar to those for the high-cost environment. Finally, setting the low value of T to be greater than the participation component for any one of the strategies would have been interesting but we decided to consider a scenario where incentives to participate are enhanced since, in the high-cost setting, participation barriers are substantial. Given this setup, we have two hypotheses:

HYPOTHESIS I: (TC1) Participation levels are lower in the high transaction cost treatment compared to the low transaction cost treatment.

HYPOTHESIS II: (TC2) Conditional upon choosing to participate, choice of the Pareto efficient equilibrium action is more frequent in the high transaction cost treatment compared to the low transaction cost treatment.

Moreover, the individual's land use choice, and hence the ability of the AB scheme to reach the efficient outcome and maximize ecosystem services benefits, is influenced by the degree of community-level social interactions. Communication between neighbors incurs costs (e.g., of time spent calling neighbors), but can provide an opportunity to (i) announce and declare sustained commitment for a particular action, (ii) articulate reasons for having made a choice in the past as well as those which will guide future decisions, (iii) influence direct neighbors to choose the same strategy, and (iv) convince direct neighbors to convince other social peers to make the same choice. Thus, communication might lead to a higher uptake, avoid coordination failure and improve the ability of the scheme to generate the Pareto efficient Nash equilibrium configuration. This is particularly true for the high-cost setting where there is no coordination problem and the only bottleneck is the participation hurdle. Our third hypothesis is consequently:

HYPOTHESIS III (Communication): Communication between neighboring landowners leads to (a) higher participation levels, and (b) given participation, improves coordination on the Pareto efficient equilibrium.

# 3. Experimental Design and Procedures

We report data from 24 sessions with 8 subjects per session, producing a data set with 192 subjects. The experimental session was divided into two phases – Phase I and II, consisting

of 15 periods each. In Phase I of 12 sessions termed HLTC (abbreviating *High-Low Transaction Cost*), subjects faced the high transaction cost of 40, followed by the low cost of 15 in Phase II. In the remaining 12 sessions termed LHTC (abbreviating *Low-High Transaction Cost*), the cost ordering was reversed. We implemented this within-subject variation because (*i*) transaction costs associated with the same economic decision may change over time, (*ii*) to minimize within-subject variation for comparison across treatments and (*iii*) to study behavior of inexperienced subjects and subjects with some prior experience with a particular cost value.

Non-binding pre-play communication, denoted by COMM, was implemented as a between-subject treatment in 8 of the 24 sessions. Each subject could communicate privately in chat windows with adjacent neighbors for 60 seconds by paying a fee of 5 experimental francs per neighbor.<sup>3</sup> Subjects could receive messages from neighbors for free despite having chosen not to communicate. This communication protocol is similar to the one implemented in Cooper et al. (1989) and represents the reality that communication is almost always costly for the sender whereas receiving messages (an email, voicemail or written communication) incurs minimal cost. This experimental design is summarized in Table 2.

At the beginning of the experiment, every subject received a randomly-assigned ID that determined their location and their networked neighbors' identities. This ID remained the same in Phase I. We implemented this fixed-matching protocol because private land ownership is usually unchanged for long time periods and also because repeated interactions with the same set of subjects can foster coordination by building subjects' reputation for playing a particular strategy amongst their direct neighbors. At the beginning of Phase II the neighborhood structure was shuffled and every subject received a new ID and a new set of neighbors which remained

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<sup>&</sup>lt;sup>3</sup> We kept chat windows open for 60 seconds to ensure that even if subjects chatted in all 30 periods, the experiment would not last for more than 90 minutes beyond which subject fatigue might compromise the quality of responses.

unchanged henceforth. This ID switch was implemented to break any possible path dependence that is often present in coordination game experiments (Van Huyck et al., 1991; Romero, 2015). This path dependence can confound the transaction cost variation treatment when transitioning from Phase I to Phase II. During each phase of the experiment, subjects received hand-outs (see Appendix B.III) containing information on the payoffs, the transaction cost of participation associated with that phase (15 or 40), the reservation (non-participation) income (175), and a figure representing their positions on the network.

In the COMM treatment, at the beginning of a period subjects first decided whether they wanted to pay the fee to communicate with their neighbors. Those who chose not to pay the fee waited for others to finish chatting. After this stage, everyone made their participation decisions. In the periods of the NO-COMM sessions, everyone proceeded to the participation stage directly. In this stage each subject had to decide whether to participate in the AB scheme by incurring the transaction cost. Neighbors' participation decisions were not revealed while subjects made this decision.<sup>4</sup> Individuals who chose to participate moved on to the next stage in which they selected land use *X* or *Y*. The ones who did not participate earned the reservation income.

Once all choices were made, subjects received information about their own and their direct neighbors' communication decisions, participation, land use choices and payoffs for the current period. Additionally, an on-screen History table provided this information for all past periods within a phase. In the COMM sessions, this History table also included subjects' own and neighbors' current and past communication decisions, and the total fees paid to communicate.

<sup>&</sup>lt;sup>4</sup> By following this approach, we were able to retain the simultaneous move feature of the coordination game although it comprised of two stages of decision-making.

We used content analysis methodology to analyze all messages from the COMM sessions. Three undergraduate students from the University of Nebraska-Lincoln reviewed chat content incorporated in 195 different chat rooms representing both dialogues and monologues. Rather than reviewing individual chat sentences separately, all messages within a chat room were encoded jointly and classified into different categories on the basis of a message classification scheme. The classification scheme was developed on the basis of review of two randomly drawn COMM sessions (for each transaction cost ordering). The content of each chat room could be assigned to multiple categories. In order to minimize bias, the coders coded statements without being aware of the research questions and were not permitted to interact with each other during the coding exercise.

Since the coding is subjective, we measured inter-rater agreement using Cohen's Kappa (Krippendorff, 2004; Cohen, 1960). This is a scaled measure of agreement and takes a value of 0 when the agreement between coders is implied by random chance and 1 when the coders agree perfectly. Kappa values between 0.41 and 0.60 indicate that coders have Moderate agreement for that category, those between 0.61 and 0.8 indicate Substantial agreement and beyond that implies Almost Perfect agreement (Landis and Koch, 1977). Table 3 presents a sub-set of categories which are coded with at least Moderate reliability and have a relative frequency across chat rooms of 15% or higher.<sup>5</sup>

The experiment was implemented in z-Tree (Fischbacher, 2007) and subjects were recruited from the broad undergraduate Purdue University population using ORSEE (Greiner, 2015) during August 2013 and November 2014. All instructions (included in the Appendix B.II) were made available on subjects' computer screens. We did not include any contextual

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<sup>&</sup>lt;sup>5</sup> We did consider other categories and sub-categories in our analysis, but they were coded with less than "Moderate" agreement and hence are not presented in the paper.

terminology relevant to ecosystem services provision other than land use because we wanted to study how financial incentives impact experimental outcomes and also because proenvironmental terminology can potentially trigger various subject behaviors and confound the treatment effect (Cason and Raymond, 2011).

Instructions (see Appendix B.II) indicated that all subjects would be facing the same payoff table, that all AB scheme payoffs were net of the transaction costs of participation, and that the experiment would repeat for 30 periods.<sup>6</sup> Before starting the experiment, subjects participated in a quiz to verify their understanding. The sessions lasted between 60 and 90 minutes. Subjects were paid a \$6 show-up fee and money made during the experiment. An exchange rate of US\$1 for 250 experimental currency (francs) was used to convert earnings, and average subject earnings (including the show-up fee) was \$26.82.

### 4. Experimental Results

Our results focus on the role of transaction costs and communication on (a) participation levels in the AB scheme, (b) the rates of efficient land use choice, and (c) the degree of spatial coordination on the efficient land use choice. In Section 4.1, we present the results related to the first two aspects followed by the findings related to spatial coordination in Section 4.2.

# 4.1. Participation and Efficient Land Use Choices

Consider first the findings from the non-communication (NO-COMM) sessions. The top two panels of Figure 1 present the participation rates in the two 15-period phases for both the cost treatments pooled across the 16 NO-COMM sessions. Participation rates are always higher

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<sup>&</sup>lt;sup>6</sup> To ensure that subjects knew that all payoffs were net of transaction costs, we clearly indicated their total payoff for each outcome in the experimental handout provided to them.

under low transaction costs in both Phases of the experiment. These rates fall steadily from 70% in Period 1 to 20% in Period 15 in the HLTC-NO-COMM sessions. By contrast, subjects in LHTC-NO-COMM sessions are able to maintain relatively higher levels of participation with only a weak negative trend in Phase I. A non-parametric Wilcoxon Mann-Whitney test based on session-level average rates of participation in Phase I indicates a statistically significant treatment effect at the 5% level (p-value = 0.015). This result provides support for Hypothesis I. The weak negative trend for the low-cost setting also indicates that transaction costs are less problematic at low values when considering participation in the AB scheme.

**Result 1:** *High transaction costs can significantly reduce participation rates in the AB schemes.* 

The falling rates of participation with repeated interactions under both cost conditions may be attributed to factors that resolve subjects' strategic uncertainty (in favor of non-participation) and impact the likelihood of participation. First, unlike in a non-network coordination game, both direct and indirect neighbors influence payoffs but only past choices of direct neighbors are visible. The second factor is that, given the structure of the payoffs, participation and subsequent coordination on X is profitable only when both direct neighbors participate. This feature is true for both high and low transaction cost values, but losses induced by coordination failure are greater when costs are high.

<sup>&</sup>lt;sup>7</sup> All nonparametric tests reported in the paper employ independent 8-person groups as the unit of observation.

<sup>&</sup>lt;sup>8</sup> We adopted this feature to evaluate the performance of the AB scheme in an adverse payoff setting with the expectation that if the incentive scheme performs well in the current environment, it will perform even better in scenarios where efficient coordination is profitable even if only one or a few neighbors choose *X*. Moreover, this adverse payoff situation also reflects recent reductions in PES scheme budgets, which require resources to be spread thinly over numerous existing programs (Shortle et al., 2012).

The experiment's two treatment phases are useful for evaluating how subjects' prior experience with a particular transaction cost regime affects participation. After the cost treatment switchover, in the HLTC-NO-COMM the participation rate jumps substantially from 20% in Period 15 to nearly 86% in Period 16. This increase is statistically significant (Wilcoxon matched-pairs signed-rank test *p-value* = 0.013). The corresponding change from 78% to 80% for the LHTC-NO-COMM group is, however, not statistically significant (Wilcoxon matched-pairs signed-rank test *p-value* = 0.943). This result suggests a path dependence in outcomes. Focusing on overall trends across all Phase II periods, we observe only a small decrease in participation in the HLTC-NO-COMM from 85% in Period 16 to 78% in Period 30. For the LHTC-NO-COMM treatment, a fall in program uptake occurs from 79% in Period 16 to 36% in Period 30. However, no significant difference exists in participation rates between the HLTC-NO-COMM and LHTC-NO-COMM groups in Phase II (Wilcoxon Mann-Whitney test *p-value* = 0.14). To summarize:

**Result 2**: Prior experience with low transaction costs reduces the negative impact of a transaction cost increase on future participation rates, moderating the effect of transaction costs as an obstacle for participation.

Figure I in Appendix A shows the percentage of X, Y and NP choices for both treatments for all periods. We observe 21% of Y choices when transaction costs are low and only 4% when costs are high in the NO-COMM groups. Thus, conditional on participation, most subjects select the efficient X strategy. The top panel of Figure II in Appendix A displays the percentage of X choices conditional on participation for both phases for both cost treatments for the 16 NO-

COMM sessions. Wilcoxon Mann-Whitney tests indicate no significant difference in the rate at which X is chosen between high and low cost costs groups in both Phases I (p-value = 0.461) and Phase II (p-value = 0.368). Accordingly, our data does not provide support for Hypothesis II. The payment of the transaction cost regardless of its value generally leads to efficient X strategy choices in groups. This result is true for any level of subject experience.

Next consider participation rates and efficient land use choice *X* in the COMM sessions. The two bottom panels of Figure 1 display participation rates for the 8 COMM sessions under the two transaction cost ordering treatments for all periods across both phases. No discernible time trend exists in any phase, and the participation is higher when transaction costs are lower (after few initial periods). For an understanding of these outcomes, we analyze the nature of communication. Figure 2 presents information about the timing and fraction of instances in which subjects paid the fee to communicate with one or both neighbors under each cost condition.

In the 195 chat rooms used, there is a predominance of dialogues (69 instances constituting 138 chat rooms) rather than monologues (57 chat rooms). This is not surprising as a dialogue is a more credible form of interaction, because players exchanging messages with each other have a stronger chance of agreement than in a monologue where the messaging player has no way of knowing if the receiver will respond appropriately. Yet in our context, the communication fee elevates the credibility of messages conveyed through monologues, both for the senders and receivers. For the receiver, the fee paid by the sender may signal commitment to the message content and for the sender it can serve as a commitment mechanism to follow through with what is communicated. Focusing first on the timing of communication, Figure 2

<sup>&</sup>lt;sup>9</sup> We also ran 8 sessions under both cost orderings where communication was free and observed participation and efficient choices very near 100%. We do not report these additional results in the interests of brevity.

indicates that most messaging occurs in Phase I (nearly 65% of all chat rooms) when subjects are unfamiliar or have low levels of experience in the experiment. The remaining 35% of messaging instances occur early in Phase II when subjects are re-assigned to new neighbors.

Turning to the communication content, Table 3 presents the different categories and subcategories into which the messages were classified and the relative frequency of these categories. The most common category coded is "Influence neighbors to choose Strategy X" (Category 4X) with a frequency of 44%; i.e., in 44% of the chat rooms a subject tried to influence a neighbor to select strategy X. The next common category is "Discuss experimental game features and payoffs" (Category 10). This category mainly includes messages that explain the value of coordination on strategy X to neighbors. The category "Declare one's commitment to select Strategy X" (Category 1X) is coded with an average frequency of 28% and is often combined with Category 4X. Finally, Category 8, denoting "Ask neighbors to influence their other neighbor's future strategy choice", has a frequency of 18%. These frequently used categories represent the overarching goal of communication – namely to reduce strategic uncertainty in favor of a strategy and to generate sustained commitment for that strategy. The choice data confirm that communication is successful because relative to NO-COMM settings, little negative time trend exists in participation rates (Figure 1 bottom panel) and a weak or no time trend exists for X choices conditional on participation (Figure II bottom panel).

To evaluate the impact of transaction costs on participation in the presence of communication opportunities, we analyze participation decisions using 2-way clustered logit regressions for both phases. The dependent variable is the likelihood of participation in a period. The control variable is the dummy variable taking a value of 1 for the high cost sessions. <sup>10</sup> The standard errors are clustered by subject and period (Cameron et al., 2011). The regression results

<sup>10</sup> We do not control for learning effects since Figure 1 (bottom panel) does not indicate any trend in the data.

are presented in the left two columns of Table 4 and suggest no significant transaction cost treatment effect in Phase I and a negative and significant effect in Phase II at 1% significance level. This result provides partial support (in Phase II only) for Hypothesis I for the COMM treatment. Note that this result contrasts with the finding in the NO-COMM treatment, where the treatment effect is found in Phase I only.

In the COMM groups subjects use communication to encourage their neighbors to participate, to generate commitment for choosing the efficient strategy, and to ensure that the willingness to participate and the commitment to choose *X* is passed on to other parts of the local network through direct and indirect neighbor linkages. This implies that in Phase I communication allows groups to sustain a stable participation rate over repeated interactions even with high transaction costs. Combined with the fact that participation rates remain high and stable in the low cost groups, no treatment effect emerges in Phase I. In Phase II after the treatment switchover, participation rates remain near the level observed during Phase I in the LHTC-COMM groups. For the HLTC-COMM groups, nearly everyone now participates owing to improvement in cost conditions. This situation leads to a significant cost treatment effect in Phase II.<sup>11</sup>

Considering differences in behavior driven by the communication treatment, relative to NO-COMM we can draw two conclusions from Figure 1. First, the participation rate is on average higher with communication than without it under both transaction cost conditions. Second, communication plays a more important role in the high transaction cost groups than in the low cost groups. Communication in high-cost groups averts the negative trend observed in the corresponding groups without communication in both phases, whereas in the low-cost groups

 $<sup>^{11}</sup>$  Conditional on participation, regression results indicate that more individuals choose X in high cost groups than in low cost groups in the presence of communication. This provides support for Hypothesis II for the communication treatment. However, for the sake of brevity we do not report these results in greater detail.

behavior is relatively stable both with and without communication. For a statistical analysis of these claims, we employ 4 clustered logit regressions (one for each Phase and transaction cost condition). The dependent variable is again the likelihood of participation, which is regressed on a dummy variable taking a value of 1 for the COMM sessions, the reciprocal of the Period variable to control for learning and capture the time trends, and an interaction term between these two variables to control for differences in learning rates between treatments. All standard errors are clustered by subject and period. The results are presented in the four left columns of Table 5.

A positive and significant estimate (at the 1% level) is obtained for the communication treatment dummy variable in both phase regressions for the high cost condition and for Phase II of the low cost treatment, providing partial support for Hypothesis IIIa. The positive estimate for the reciprocal of the period variable and the negative estimate for the interaction term for both phases of the high-cost treatment and Phase I of the low-cost treatment signify the impact of experience on participation. Thus, relative to no-communication scenarios, communication has an unambiguously positive effect under unfavorable participation conditions and its benefits under low-cost conditions are obtained only when subjects have had no prior experience with participation in the AB scheme. To summarize:

**Result 3:** Communication generates greater rates of participation in the AB scheme. Communication has a greater positive impact when compared to the no-communication setting in high-cost groups at all levels of subject experience than in low-cost groups.

## 4.2 Spatial Coordination

This section presents an analysis of location-specific land use choices of all participants to assess the performance of the AB in creating spatially coordinated land use patterns. We develop a performance metric counting every instance where a subject and their two direct neighbors within their local neighborhood are able to *locally coordinate* on the same land use strategy. This metric can take a maximum value of 8, signifying that all 8 group members are perfectly or *globally coordinated* on either strategy *X* or *Y*. Any other lower non-zero value indicates only localized clustering of similar choices on the network. In this format, the same metric captures instances of both local and global coordination that are routinely observed in all groups during the experiment. Since coordination on *X* is Pareto efficient, we refer to this as locally *efficient* coordination.

Let us start by examining spatial coordination under the no-communication regime. The top two panels of Figure 3 present the average levels of locally efficient coordination by a subject and both their neighbors in the NO-COMM groups for all periods of Phases I and II. Localized coordination on X is of special interest for the high-cost condition since the non-participation strategy NP strictly dominates option Y. For these groups, post-participation, the selection principle of forward induction guides many adjacent subjects' choices to the Pareto efficient X equilibrium. While forward induction may not explain the many adjacent X choices in the low-cost groups, the upfront communication fee payment focuses multiple neighboring subjects' choices on X, which pays more than Y in the event of localized coordination.

A Wilcoxon Mann-Whitney test detects a significant difference in efficient localized coordination between low and high-cost groups without communication (p-value = 0.05) in Phase I after Period 8. A likely reason for this outcome is that in the initial periods subjects are unfamiliar with the strategic environment, as a result of most X choices being either non-adjacent

or involving only two neighbors selecting *X*. With repeated interactions participation rates fall in both groups, but they fall more steeply in the high-cost sessions (as an increasing number of subject's strategic uncertainty gets resolved in favor of *NP*) causing fewer neighbors to choose *X*. As a result, rates of localized efficient coordination fall to about 14% in Period 15 in HLTC-NO-COMM groups. Performance is maintained between 40% and 50% in the LHTC-NO-COMM groups, where more people choose X and the participation rate has a weak negative trend, leading to the significant treatment effect. In Phase II there is no significant difference across transaction cost treatments, consistent with the previous result regarding no significant difference in participation rates.

The left panel of Figure 4 presents the fraction of instances of globalized efficient coordination for the NO-COMM sessions, defined as all eight group members choosing *X*. Wilcoxon Mann-Whitney tests indicate no significant cost-treatment effect in either Phase. Group-level coordination is difficult – regardless of the transaction cost value, it is challenging to get all group members to make the same choices, especially given that information feedback is limited to direct neighbors only. Yet, positive rates of global coordination suggest that, despite participation challenges, the AB scheme can sometimes fully coordinate environmentally-beneficial choices.

**Result 4**: Greater transaction costs reduce localized efficient coordination only for inexperienced groups and globalized efficient coordination is not significantly impacted by variation in the transaction cost values.

Let us now compare rates of spatial coordination with communication. The bottom panel of Figure 3 shows the percentage of localized coordination in the COMM groups by transaction cost and for both phases. A surprising result is that in Phase I, localized coordination is greater in the HLTC-COMM groups relative to the LHTC-COMM groups. This difference is weakly statistically significant at the 10% level on the basis of a 2-way clustered logit regression (Table 4, third column) where the dependent variable takes a value of one when players within a local neighborhood are able to coordinate on the efficient strategy *X* and 0 otherwise, and the independent variables are the high cost treatment dummy and the reciprocal of the period variable included to capture non-linear rates of learning. Thus, although in Phase I there is no difference in the number of individuals who participate under the two cost conditions, more neighbors participate in high-cost than in low-cost groups. Localized coordination (and global coordination) is improved in low-cost groups in Phase II relative to high-cost groups since virtually every individual in the HLTC-COMM group participates and nearly everyone chooses *X*. The rightmost column of Table 4 shows that this difference is statistically significant at the 1% level on the basis of a 2-way clustered logit regression.

Finally, we compare localized coordination rates with and without communication. The four right columns of Table 5 present the results of four 2-way clustered logit regressions (for each Phase and transaction cost condition). The dependent variable is an indicator taking a value of one when players within a local neighborhood are able to coordinate and choose *X*. Similar to the previous models, the control variables include a dummy variable taking a value of 1 for the COMM sessions, the reciprocal of the period variable and an interaction term. Results indicate a significant (at the 1% level) and positive estimate for the COMM dummy variable in both phase regressions for the high transaction cost condition and for the low-cost condition in Phase II,

substantiating the information presented in Figure 3 when comparing across top and bottom panels for each cost condition and phase.

Relative to no-communication settings, messaging (with the aim to build commitment for and coordination on strategy X as highlighted by the communication analysis) can guide behavior of a greater number of adjacent individuals to the efficient choice, hence significantly improving the likelihood of localized efficient coordination. For groups facing low transaction costs, the COMM dummy variable is not significant in Phase I which is in line with Result 3. Moreover, the signs of the estimates for the interaction term and the reciprocal of the period variable for the high-cost models indicate that repeated interactions improve performance in groups with communication. Since the negative trend is largely a result of strategic uncertainty being resolved in favor of NP and communication reduces strategic uncertainty in favor of participation and X, this result follows automatically. This finding is consistent with Hypothesis III(b) and underscores the positive role of communication in guiding the selection of the efficient Nash equilibrium outcome in coordination games with both Pareto-dominant and risk-dominant Nash equilibria within a local network setting. In summary:

**Result 5**: Mechanisms to reduce strategic uncertainty, such as communication, can build commitment for choosing the efficient strategy and improve AB performance in the presence of transaction costs.

# 5. Discussion

Our study results are of course predicated on the nature of the strategic environment, i.e., the payoff functions under both transaction costs, the size and circular nature of the local network, and the degree of information feedback. A circular network does not describe many real world settings where an AB policy could be introduced. Using a spatial set-up different from the circular network (such as a line or lattice) may produce different results, since some individuals would have different numbers of neighbors, and would therefore face different levels of strategic uncertainty and payoffs. In the context of coordination games, Cassar (2007) finds that the frequency of payoff-dominant choices is higher in a "small world" or a "random" network than in a local network such as the one we consider. She also finds that coordination is obtained much faster in the small world setting, while noting that "a theory linking network characteristics to individual behavior is not yet available" (page 228). However, compared to networks where strategic uncertainty varies across players, we could argue that the circular network provides a lower bound on coordination failure in an AB setting.

We could have chosen a transaction cost value less than 40, which would not have made *Y* strictly dominated by *NP*. We conjecture that there would then be much greater participation and many more *Y* choices than is currently observed under the high-cost treatment. While this is interesting, this finding is similar to results obtained in Banerjee et al. (2014) and could have eliminated (*i*) any difference between high-cost and low-cost groups and (*ii*) subjects' ability to use forward induction to guide their behavior in our network AB coordination game. Moreover, the transaction cost treatment is more interesting if it generates differences in the strategic situation compared to when it just produces a difference in net payoffs.

The size of the circular network and nature of information feedback may also impact behavior. More information and smaller group sizes usually generate greater rates of efficient choices in coordination games. However, with a group size of 8 we believe we have struck a middle ground whereby the group is small enough for many individuals to choose *X* and large

enough for many to select *NP* (owing to high strategic uncertainty) or *Y*. With this group size we are able to assess the extent to which the AB can still deliver on its environmental goal when the effect of each individual is relatively small compared to the total group. Finally, we could have provided information to subjects beyond their local neighborhoods (e.g., on their indirect neighbors such as in Banerjee et al., 2014). However, that would be inconsistent with our localized communication format although it provides a future avenue for research especially if regulatory agencies start publicly announcing enrollment rates in order to promote greater participation. It is also possible that coordination failure would have implications for what participants consider "fair", and that this would influence the likelihood of coordination on the Pareto-superior equilibrium, especially if outcomes are observable such as in Reeson et al. (2011).

#### 6. Conclusions

PES schemes are increasingly being implemented as policy mechanisms to enhance the supply of ecosystem services. The predominant property rights regime in countries such as the US, the UK, New Zealand and Australia requires that landowners be financially compensated to encourage the supply of ecosystem services, rather than being compelled to do so by regulation: the "provider gets" principle (Hanley et al., 1998). Second, for many environmental outcomes, spatial coordination increases the size of environmental benefits for a given level of enrollment in voluntary conservation programs. The policy design challenge is then to find systems of incentives which spatially coordinate a voluntary sign-up program. The Agglomeration Bonus (AB) is one such mechanism. However, the AB faces a number of potential problems, including the tendency over time for participants to converge on risk-dominant outcomes, a lack of cost-

effectiveness, and, like many incentive programs, the size and nature of transaction costs. To date, the effects of transactions costs have not been investigated in the AB literature, despite their importance to PES scheme participation decisions.

In this paper we use a laboratory experiment to investigate how private transaction costs affect the degree of participation in an AB scheme, its efficiency and the patterns of spatial coordination in the presence and absence of communication. Results show that higher transaction costs lead to greater non-participation, whilst lower transaction costs are conducive to producing a greater degree of coordination on the most preferred environmental outcome. Full coordination on the most efficient outcome is rarely achieved, but localized clusters of coordinated conservation actions emerge in most cases.

Communication through payment of a fee improves outcomes, generating economic and environmental benefits. There are clear parallels here with experimental findings on the implications of communication (albeit costless) in "ambient" or Segerson-type pollution tax schemes (Segerson, 1988), where the pollution tax liability of each firm depends on group behavior. For example, Suter et al. (2008) find that allowing participants to communicate in a non-binding fashion produces lower pollution levels and maximizes group profits. Our communication results can also be compared with the effects of costless communication in experiments on Voluntary Contribution Mechanisms for public goods, such as in Isaac and Walker (1988), where non-binding group discussion significantly reduced free-riding behavior.

The policy implications of our results are clear: if the regulator can design an AB scheme in a way which keeps transaction costs low relative to the payoffs of coordination, then it will be easier to achieve spatial coordination (both locally and globally). This, in turn, enhances a more effective delivery of ecosystem services. However, if achieving a given environmental objective

requires writing (complicated) rules for potential participants, then there is a trade-off between improving environmental effectiveness and increasing coordination, since such complications will increase transactions costs. Set against this scenario, facilitating low-cost communication between landowners would improve the likelihood of successful coordination towards socially-desirable land use patterns. Providing subsidies to lower transaction costs initially could foster early coordination, and our results suggest that improved performance could persist even after such subsidies are removed and transaction costs increase.

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# **TABLES**

**Table 1a: Payoff Table for High TC condition** 

# **Payoff Table**

# **Actions Chosen by Neighbors**

Your Action	Both Participate Participate Choose X Chooses X & other Y		Both Only one Participates and & Chooses Choose Y X		Only one Participates & Chooses Y	No Neighbor Participates
X	210	125	40	125	40	40
${f Y}$	145	155	165	145	155	145
NP (Non- Participation)	175	175	175	175	175	175

**Table 1b: Payoff Table for Low TC condition** 

# **Payoff Table**

# **Actions Chosen by Neighbors**

Your Action	Both Participate Choose X	Both Participate & one Chooses X & other Y	Both Participate & Choose Y	Only one Participates & Chooses X	Only one Participates & Chooses Y	No Neighbor Participates
X	235	150	65	150	65	65
$\mathbf{Y}$	170	180	190	170	180	170
NP (Non- Participation)	175	175	175	175	175	175

**Table 2: Summary of Experimental Design** 

	<b>Communication Treatment</b>			
Transaction Cost Ordering Treatment	No-Comm	Comm		
High-Low	HLTC-No-Comm (8 sessions)	HLTC-Comm (4 sessions)		
Low-High	(8 sessions)  LHTC-No-Comm  (8 sessions)	LHTC-Comm (4 sessions)		

Table 3: Categories for coding messages (reaching at least Moderate reliability) and observed frequency in chat rooms

Category <sup>+</sup>	Description	Cohen's Kappa	Reliability	Relative Frequency of Coding
1	Declare one's commitment to a particular strategy			
1X	Will select X	0.83	Almost Perfect	0.28*
1Y	Will select Y	0.90	Almost Perfect	0.03
1NP	Will select NP	0.75	Substantial	0.06
2	Explain own reason for choosing a strategy (X, Y or NP)			
2P	In the past periods	0.45	Moderate	0.02
3	Inform one neighbor about other neighbor's strategy choice			
3X	Other neighbor chose X	0.45	Moderate	0.03
3Y	Other neighbor chose Y	0.79	Substantial	0.03
3NP	Other neighbor chose NP	0.69	Substantial	0.04
3NX	Other neighbor did not chose X	0.56	Moderate	0.03
4	Influence neighbor(s) to select a particular strategy			
4X	Choose X	0.81	Almost Perfect	0.44*
4Y	Choose Y	0.78	Substantial	0.02
4NP	Choose NP	0.79	Substantial	0.01
5	Ask neighbors about their future choices	0.55	Moderate	0.07
6	Ask neighbors about their reasons for choosing a strategy	0.65	Substantial	0.03
7	Ask neighbors about their other neighbors past choices	0.53	Moderate	0.02
8	Ask neighbors to influence their other neighbor's future strategy choice	0.88	Substantial	0.18*
8X	Influence other neighbor to select X	0.89	Almost Perfect	0.17
8Y	Influence other neighbor to select Y	0.49	Moderate	0.00
9	Refer to own past strategy choice	0.49	Moderate	0.01
10	Discuss about experimental features & game payoffs	0.73	Substantial	0.33*
11	Agree on a strategy	0.55	Moderate	0.13
12	Other	0.54	Moderate	0.34*

<sup>&</sup>lt;sup>+</sup> Only those categories (and sub-categories) reaching an agreement of Moderate of higher are listed. *X* and *Y* labels correspond to Strategies *A* and *B* in the experiment.

<sup>\*</sup> Represents categories which have a relative frequency of coding of 15% or more.

Table 4: 2-way Clustered Logit Regressions for Participation and Performance Analysis in each Phase for Communication Groups

Dependent Variables	Partic	ipation	<b>Localized Efficient Coordination</b>			
Independent Variables	Phase II Phase II		Phase I	Phase II		
High Cost	-0.024 (0.019)	-0.157** (0.032)	0.027* (0.015)	-0.106*** (0.023)		
1 Period <sup>+</sup>	-	-	-1.343** (0.344)	-0.756** (0.048)		
Constant	2.161** (0.612)	7.43** (1.15)	-0.098 (0.478)	1.975*** (0.49)		
Number of observations	960					

**Cluster Variables** 

Individual Subject and Experimental Period in a Phase

Table 5: 2-way Clustered Logit Regressions for Performance comparison of Communication and No Communication Treatments by Phase and Transaction Cost

Independent	Participation				<b>Localized Efficient Coordination</b>			
variables	Phase I	Phase II	Phase I	Phase II	Phase I	Phase II	Phase I	Phase II
	(HC)	(LC)	(LC)	(HC)	(HC)	(LC)	(LC)	(HC)
Comm	0.892***	1.999***	0.197	0.782***	1.063***	2.019***	0.028	0.864***
	(0.229)	(0.622)	( 0.245)	(0.246)	(0.221)	(0.374)	(0.192)	(0.237)
$\frac{1}{Period^+}$	2.197**	0.428	1.960***	2.674***	0.027	-0.368	-1.152***	0.610**
	(0.871)	(0.421)	( 0.652)	(0.902)	(0.458)	(0.227)	(0.381)	(0.252)
1 Period+ x Comm	-1.060** (-0.467)	-1.094 (0.81)	-1.285*** (0.356)	-1.179*** (0.489)	-0.848** (0.368)	-0.375 (0.658)	0.078 (0.327)	-0.652*** (0.095)
Constant	-0.600**	1.579***	1.549***	-0.5*	-1.088***	-0.086	0.171	-0.546**
	(0.29)	(0.251)	(0.29)	(0.26)	(0.297)	(0.728)	(0.449)	(0.245)

Number of Observations

Cluster Variables

Individual Subject and Experimental Period in a Phase

<sup>\*\*</sup> Represents statistical significance at the 1% level, \* at the 10% level

<sup>+</sup> Period takes a value between 1 and 15

<sup>\*\*\*</sup> Represents statistical significance at the 1% level, \*\* at the 5% level and \* at the 10% level

<sup>+</sup> Period takes a value between 1 and 15

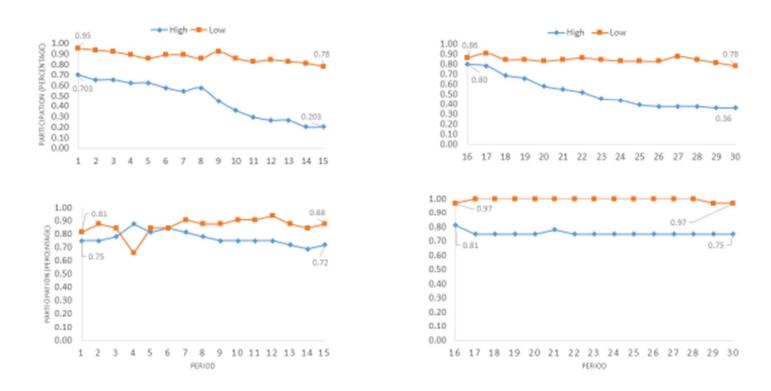


Figure 1: Percentage of Participation in Phase I & Phase II of No-Comm (top panel) and Comm (bottom panel) Sessions by Transaction Costs Treatment

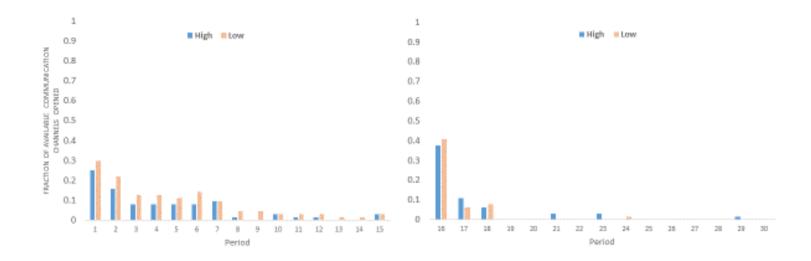


Figure 2: Fraction and Timing of Communication Channels opened with One or Both Neighbors by Phase and Transaction Cost

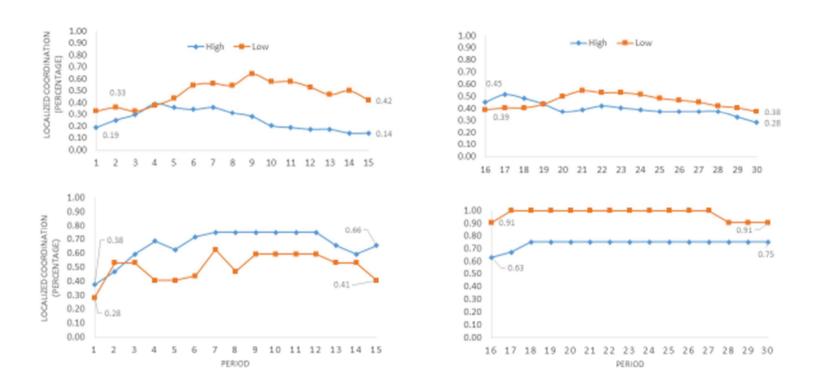


Figure 3: Percentage of Localized Efficient Coordination (player and direct neighbors choose X) in Phase I & Phase II of No-Comm (top panels) and Comm (bottom panels) Sessions by Transaction Costs Treatment

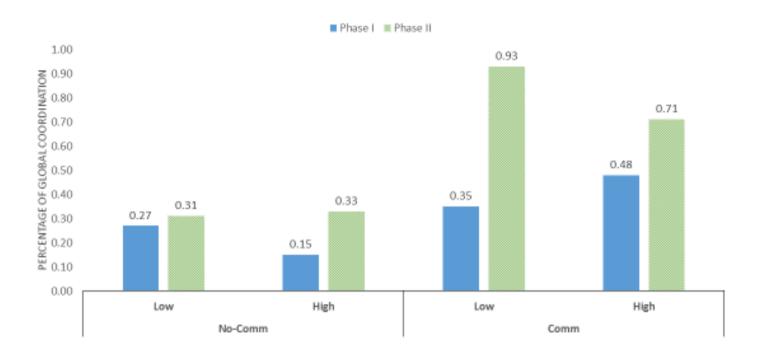


Figure 4: Perfect/Global Efficient Coordination (the whole group chooses X) in all treatments for both Phases

#### 1.00 0.90 0.82 0.76 0.80 0.60 0.50 0.40 0.30 0.64 0.51 0.45 0.24 0.21 0.20 0.11 0.07 0.10 0.04 0.00 0.00 High High Low Low No-Comm Comm X Y NP

Appendix A

Figure I: Percentage of Choices Pooled over Time for All Treatments

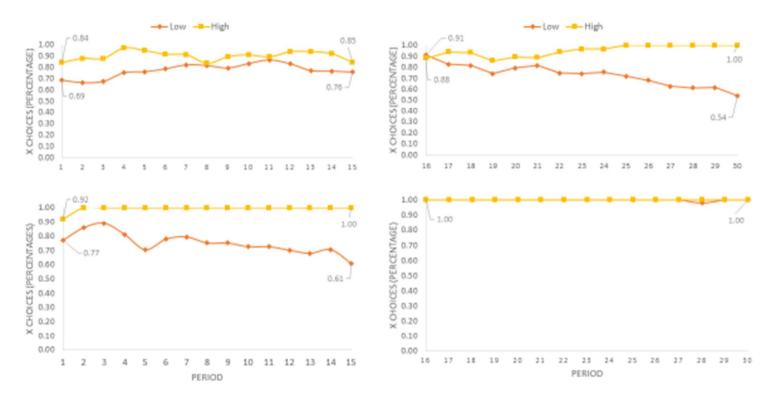


Figure II: Percentage of X Choices in Phase I & Phase II of No-Comm (top panels) and Comm (bottom panels) Sessions by Transaction Costs Treatment contingent on Participation

# **Appendix B.I: Parameters used to create Payoff tables**

Income from NP = 175

Agricultural Income from choosing X: 60

Agricultural Income from choosing Y: 80

Participation Payment for choosing *X*: 20

Participation Payment for choosing Y: 105

Agglomeration Bonus Payment for choosing X: 85

Agglomeration Bonus Payment for choosing Y: 10

High Transaction Cost: 40

Low Transaction Cost: 15

### **Appendix B.II: Instructions for HLTC Sessions**

(Text in italics represents instructions for Comm Sessions. The X and Y strategies referred to in the paper correspond to the strategy labels A and B in the instructions)

# Thank you for participating in today's experiment

Your unique Identification number - ID for this experiment is 1. This number is private and should not be shared with anyone. You will have this ID for the next 15 periods of the experiment.

Please click "OK" when you are ready.

## **General Information:**

This is an experiment in decision making. In today's experiment you will participate in a group decision task. In addition to a \$6 participation fee, you will be paid the money you accumulate from your choices which will be described to you in a moment. Upon the completion of the experiment, your earnings will be added up and you will be paid privately, in cash. The exact amount you will receive will be determined during the experiment and will depend on your decisions and the decisions of others. From this point forward all units of account will be in experimental francs. At the end of the experiment, experimental francs will be converted to U.S. dollars at the rate of 1 U.S. dollar for every 250 experimental francs.

If you have any questions during the experiment, please raise your hand and wait for the experimenter to come to you. **Please do not talk, exclaim, and look at the computer screens of other participants during the experiment**. Participants intentionally violating the rules may be asked to leave the experiment and may not be paid.

Please click "Continue" when you are ready.

#### **Today's Decision Making Task:**

The experiment will have **thirty periods**. In each period you will be in a group with **7** other participants. You and all the other players are arranged around a circle. The diagram of this circle is included in the handout that has been provided to you. The black dots on the circle represent your location. On this circle, you have two neighbors - **a right or anti-clockwise** neighbor and **a left or clockwise** neighbor. You will never know the identity of your neighbors. Your ID will determine who your neighbors are. Please keep in mind that every player has **a different** set of neighbors. Thus if you are **Player 8** then your right or anti-clockwise neighbor is **Player 7** and left or clockwise neighbor is **Player 1**. Similarly **Player 7** has **you** as their left or clockwise neighbor and **Player 6** as their right or anti-clockwise neighbor. Your ID and your neighbors will be the **same** for the first 15 periods of the experiment. At the beginning of Period 16, everyone will be provided with a different ID. As a result of this ID change, your neighbors between Periods 16 and 30 will be different from those between Periods 1 and 15. Also please remember that the person sitting at the computer terminal beside you is not your neighbor in the experiment.

During this experiment each of you will assume the role of a landowner who can participate in a land management program or opt out of it. In both cases, you will receive money for your actions. You will first be given the option to participate in this program. If you choose not to participate, you will receive a payment. **Participation is costly and so you have to incur a cost to do so.** Once you have incurred the cost, you will be able to take part in a group decision task which is part of the land management program. In this task, you will make a choice between two types of land use actions denoted by **A** and **B**. You will receive a payment based on your choice of **A** or **B**. Since this is a group decision task, your payment will depend on the choices made by your neighbors as well. In a moment we will give you a detailed description of how your payment will be determined.

Please note that you may decide to participate in the task but one or both of your neighbors may choose not to. Also while you decide to participate, you will not know what choices your neighbors' are making.

Please raise your hand if there are any questions otherwise click "Continue".

### **Your Payment from Group Decision Task:**

If you choose to participate in the land management program, then in each period of the experiment, the computer will display a table such as the one shown below. This Payoff Table will be the **same for everyone during a period. However the values in the cells will be different in different periods of the experiment.** You will be provided with a handout containing the Payoff Table. Each number in the table corresponds to a payment (**in experimental francs**) resulting from a possible combination of your choice of A or B (in the row) and your neighbors' choices (in the column). **Please note that all figures in the table are net of the participation cost, i.e., the participation cost has already been deducted from the payoffs.** For example, suppose the participation cost is 40 and your payoff from choosing A and both your neighbors participating and choosing A is 250. Then your final payoff is (250 - 40) = 210. This is listed in the first cell of the first row of the Payoff Table. Similarly if you select B after participation and only one of your neighbors participates and chooses B, the payoff is 195. Then your final payoff is (195 - 40) = 155. The last column in the table indicates your payoffs if you participate and none of your neighbors participate.

Please note that when you will be asked to participate or not, you will know the value of the cost you have to incur. In general, your payoff from the group decision task increases when you choose the same action as your participating neighbors.

Also your payoffs are the same if 1) one or both neighbors participate and choose a different strategy than you or 2) they don't participate at all. For example, the payment to you from choosing B and both of your neighbors choosing A is the same as you choosing B and none of your neighbors participating.

#### Communication stage:

Before making a choice in a period about participating in the land management program, you will have the option to communicate with one or both of your neighbors. For every person you choose to communicate with, you have to pay a fee of 5 experimental francs per person. Thus if you choose to communicate with both neighbors, you have to pay a fee of 10 francs. If you choose not to communicate, you don't have to pay the fee. Please note that it is possible that you pay the fee and choose to communicate with your neighbors but they choose not to pay the fee and communicate with you. If that is the case, you will be able to send messages to the neighbors with whom you have paid to chat and they will be able to view these messages. Similarly, you may have chosen not to chat with your neighbors but one or both of them paid a fee to chat with you. They will be able to send messages to you which you will be able to view.

Your communication with the neighbor(s) will consist of messages exchanged in "chat boxes" to the left and/or right of your computer screen depending upon which neighbor you chat with. Messages sent in this chat will only be viewed by you and the neighbor you send it to. For example, if you are **Player 8** and you and both your neighbors have paid the fee to communicate, the chat box on your left will contain messages you send to and receive from **Player 1** and that to the right will contain messages you send to and receive from **Player 7**. You will be able to send and receive chats for 60 seconds each period. In order to send a chat to your neighbors, please type in the blue panel at the bottom of your chat box and press Enter. To send a message to your left neighbor, type your chat in the left blue panel at the base of the left chat box. Similarly use the blue panel at the base of the right chat box to send chats to your right neighbor.

Although the messages you send to each other will be recorded, your ID remains anonymous and hence all communication is anonymous to the experimenter and cannot be traced back to any subject. In sending messages, you should follow two basic rules: (1) be civil to one another and do not use profanities, (2) only use your ID to identify yourself in any manner. After the chat period is over you will be able to see the chats you have exchanged with your neighbors for 10 seconds. After these 10 seconds are over, everyone will make their participation and land management decisions. Please note that you do not learn the land management decisions of your neighbors while making your own decision.

# Making a choice in a period: (No-Comm)

Once the period starts, each of you will first choose whether to participate or not. If you decide not to participate, then you will receive a fixed payoff. This payoff **does not depend** upon your neighbors' participation decisions. If you decide to participate, then in the next stage, you will choose strategy **A or B** by clicking on one of the buttons that will appear on the right of your screen. You may change your choice as often as you like, but once you click on **OK** your choice for that period is final.

Note that when you are making a choice, you will not know what choices others are making. Also, remember that you will never know the identity of anyone else in your group, meaning that all choices are confidential and that no one will ever know what choices you make.

At the end of each period after you have made your choices, your screen will display your choice and payoff. Information will also be provided about whether your neighbors participated and if they did, what

were their choices for that period. Information on your accumulated payment through the current period will also be provided. At the end of the experiment, you will receive the sum of your payments from all thirty periods converted to real dollars. This will be paid to you privately in cash.

Before starting the experiment you will participate in a quiz on the next screen. Please note that you will not earn any money from participating in the quiz i.e. this is a non-paying period. Your answers in this quiz will not influence your final payoffs at the end of the experiment.

#### Making a choice in a period: (Comm)

Once the period starts and after you have made a decision to communicate (or not), each of you will first choose whether to participate or not. If you decide not to participate, then you will receive a fixed payoff. This payoff does not depend upon your neighbors' participation decisions. If you decide to participate, then in the next stage, you will choose strategy A or B by clicking on one of the buttons that will appear on the right of your screen. You may change your choice as often as you like, but once you click on OK your choice for that period is final.

Note that when you are making a choice, you will not know what choices others are making. Also, remember that you will never know the identity of anyone else in your group, meaning that all choices are confidential and that no one will ever know what choices you make.

At the end of each period after you have made your choices, your screen will display your choice and payoff. Information will also be provided about whether your neighbors participated and if they did, what were their choices for that period. Information on your accumulated payment through the current period will also be provided. You will also receive information about your and your neighbors' communication decisions. At the end of the experiment, you will receive the sum of your payments from all thirty periods converted to real dollars. This will be paid to you privately in cash.

Before starting the experiment you will participate in a quiz on the next screen. Please note that you will not earn any money from participating in the quiz i.e. this is a non-paying period. Your answers in this quiz will not influence your final payoffs at the end of the experiment.

### **Quiz:**

- 1. Your neighbor has the same neighbors as you. FALSE
- 2. Your ID and your neighbors change in Period 16 TRUE
- 3. What is your payoff when you chose B and both of your neighbors participate and chose A? 145
- 4. If you choose not to participate, then your neighbors' actions don't impact your payoff. TRUE
- 5. When you are deciding whether to participate or not, you will know whether your neighbors are participating or not. **FALSE**
- 6. If you decide to communicate with a neighbor, you have to pay a fee of 5. TRUE

### The Payoff Table: (Phase I)

The table below represents the Payoff Table for Periods 1 to 15. If you choose to participate in the land management program, your payoffs will be determined on the basis of this table for the next 15 periods. This Payoff Table has been provided to you in the handout. You will be provided a handout with a different Payoff Table at the end of 15 periods.

The cost of participating in the land management program for the first 15 periods is 40.

If you choose not to participate, then you will receive a payoff of **175**. This payoff is not dependent on the choices of your neighbors and is the **same for all 30 periods**.

As mentioned before, all figures in the Payoff Table are net of the participation cost, i.e., the participation cost has already been deducted from the payoffs.

Your ID for the next 15 periods is 1 and your left neighbor is Player 2 and right neighbor is Player 8.

We are now ready to begin the experiment. You will be paid on the basis of all choices you make henceforth. If you don't have any further questions, please click OK to begin.

## **Results Table:** (No-Comm)

On the next screen you will be able to see two tables. The first table presents your choice (of A, B or NP) and the choices of your right and left neighbors for **the current period**. Your choice is in the cell at the center of the table. Your neighbors' choices are recorded in cells on your left and right. **NP** denotes a non-participation choice. The second table is the **History Table** and records your and your neighbors' choices and your profits for the **current period** and **all periods** of this experiment. Please raise your hand if there are any questions otherwise click "Continue".

# Results Table: (Comm)

On the next screen you will be able to see three tables. The first table records your and your neighbors' chat decisions for the current period. The second table presents your choice (of A, B or NP) and the choices of your right and left neighbors for the current period. Your choice is in the cell at the center of the table. Your neighbors' choices are recorded in cells on your left and right. NP denotes a non-participation choice. The third table is the History Table and records your and your neighbors' choices and your profits for the current period and all periods of this experiment. Please raise your hand if there are any questions otherwise click "Continue".

## The Payoff Table: (Phase II)

The table below represents the Payoff Table for Periods 16 to 30. If you choose to participate in the land management program, your payoffs will be determined on the basis of this table for the remaining 15 periods. The handout containing this Payoff Table will now be distributed to you.

The cost of participating in the land management program for the remaining 15 periods is 15.

If you choose not to participate, then you will receive a payoff of **175**. This payoff is not dependent on the choices of your neighbors and is as mentioned the **same for all 30 periods**.

As mentioned before, all figures in the Payoff Table are net of the participation cost, i.e., the participation cost has already been deducted from the payoffs.

Please remember that your new ID is **4** and your new neighbors are **Player 5** and **Player 3**. Everyone else has a different ID as well. Thus your neighbors between Periods 16 and 30 are **different** from your neighbors between Periods 1 and 15. However your neighbors during the next 15 periods of the experiment will remain the same.

Once you have received the handout, please click OK to continue.

Appendix B.III: Experimental Handout for High Cost Treatment

Your Right OR Anti-clockwise Neighbor

You You

Your Left or Clockwise Neighbor

Payoff from Non-Participation (NP): <u>175</u>

Cost of Participating in Land Management Program: 40

**Payoff Table** 

# **Actions Chosen by Neighbors**

Your Action	Both Participate Choose A	Both Participate and one Chooses A & other B	Both Participate and Choose B	Only one Participates & Chooses A	Only one Participates & Chooses B	No Neighbor Participates
$\mathbf{A}$	210	125	40	125	40	40
В	145	155	165	145	155	145
NP (Non- Participation)	175	175	175	175	175	175

All payoffs are net of participation costs